

A Phonography-Based Method Improved by Hidden Markov Model for Fetal Breathing Movement Detection

Dr. G. Sudha¹, S. Aarthi², R. Akalya³, R. Karthickraja⁴, K. Vasudevan⁵

¹Professor, Department of Biomedical Engineering, Muthayammal Engineering College, Rasipuram

²UG Final year, Department of Biomedical Engineering, Muthayammal Engineering College, Rasipuram.

Email: saarthypsenthil@gmail.com

^{3,4,5}UG Final year, Department of Biomedical Engineering, Muthayammal Engineering College, Rasipuram

ABSTRACT

Fetal breathing movement (FBM) is an essential physiological indicator used to assess fetal health, neurological maturity, and respiratory development during pregnancy. Conventional diagnostic approaches—primarily ultrasound-based biophysical profiling—are limited by short observation windows, operator dependency, high cost, and an inability to provide continuous monitoring. To overcome these constraints, this study proposes a non-invasive, phonography-based method enhanced with a Hidden Markov Model (HMM) for accurate and continuous detection of fetal breathing movements. Abdominal acoustic signals are captured using a sensitive phonographic sensor, followed by a comprehensive preprocessing pipeline involving bandpass filtering, wavelet-based noise reduction, and segmentation. Spectral and temporal features such as Mel-Frequency Cepstral Coefficients (MFCC), short-time energy, spectral entropy, and zero-crossing rate are extracted to represent breathing-related acoustic patterns. The HMM is trained to model the temporal dynamics of respiratory cycles, enabling robust classification even in the presence of maternal and environmental noise. Experimental evaluation demonstrates that the proposed HMM-based system significantly outperforms traditional rule-based and static machine learning methods, achieving high accuracy and strong noise resilience.

Keywords: Fetal Breathing Movement, Phonography, Hidden Markov Model, Biomedical Signal Processing, Prenatal Monitoring, Acoustic Analysis.

How to cite this article: Sudha G, Aarthi S, Akalya R, Karthickraja R, Vasudevan K. A Phonography-Based Method Improved by Hidden Markov Model for Fetal Breathing Movement Detection. *Int J Drug Deliv Technol.* 2026;16(51s): 1029-1036. DOI: 10.25258/ijddt.16.51s.85

Source of support: Nil.

Conflict of interest: None

I. Introduction

Fetal breathing movement (FBM) is an essential physiological activity that reflects the development and functional maturity of the fetal central nervous and respiratory systems. Clinically, FBM is one of the primary components evaluated during the Biophysical Profile (BPP), as its presence indicates healthy neurological function, adequate oxygenation, and overall fetal well-being. The absence or reduction of FBM over extended periods may indicate fetal distress, hypoxia, growth restriction, or abnormalities in neuromuscular development. Hence, accurate and timely detection of

FBM plays a crucial role in prenatal diagnosis and decision-making.

Ultrasound imaging remains the gold standard for assessing fetal breathing movements. However, ultrasound examinations are limited to clinical environments and require trained sonographers to operate the system. Moreover, the observation window is

Phonography—the process of capturing acoustic signals from the maternal abdomen—has emerged as a promising, non-invasive method for fetal monitoring. Abdominal acoustic sensors can detect subtle fetal movements, including respiratory like oscillations generated by diaphragmatic contractions. However, phonographic signals are inherently noisy, as they include overlapping sound sources such as

typically restricted to short time periods, making it difficult to capture irregular or intermittent breathing patterns. The high equipment cost and its inability to support long-duration continuous monitoring further restrict its accessibility, especially in rural or resource-limited regions.

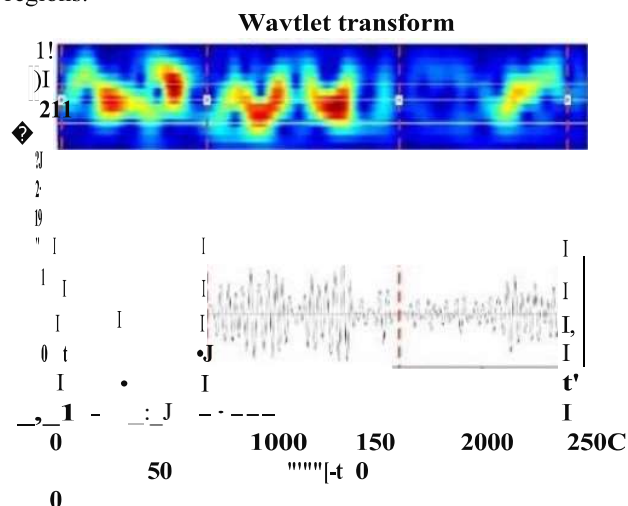


Figure 1-Wavelet transform

These limitations highlight for the growing need alternative, cost-efficient, and portable monitoring solutions capable of providing continuous assessment of FBM outside clinical settings.

maternal heartbeat, gastrointestinal activity, movement artifacts, and environmental noise. The presence of these disturbances makes accurate detection of fetal breathing a challenging signal-processing problem.

To overcome these challenges, the present study introduces a phonography-based fetal breathing detection system enhanced with a probabilistic

sequential model, specifically the Hidden Markov Model (HMM).

Unlike traditional rule-based or static classification methods, HMMs are well suited for modeling temporal and quasi-periodic biological signals. Their ability to capture sequential dependencies and state transitions enables effective discrimination between breathing and non-breathing patterns, even in noisy conditions. By integrating advanced preprocessing, acoustic feature extraction, and HMM-based classification, the proposed system aims to improve detection accuracy, robustness, and reliability.

II. Literature Review

Fetal breathing movement (FBM) detection has been extensively studied due to its importance in fetal well-being assessment. Traditionally, ultrasound-based biophysical profiling has served as the primary method for observing FBM. According to Manning et al. (1981), ultrasound imaging provides accurate visualization of diaphragmatic movement but is limited by short examination windows, operator dependency, and high cost. Furthermore, continuous monitoring is impractical due to the exposure limitations and the need for clinical supervision. These challenges have motivated the shift toward alternative non-invasive and continuous monitoring techniques.

Acoustic sensing, specifically phonography, has gained research attention as a potential modality for fetal monitoring. Schmidt et al. (2019) highlighted the feasibility of using abdominal microphones to capture fetal movement sounds, including breathing like oscillations. However, they noted that the phonographic signal is highly contaminated with maternal physiological noise, motion artifacts, and gastrointestinal activity. Earlier techniques relied on simple filtering and energy-based detection, often resulting in poor accuracy due to overlapping frequencies between fetal and maternal signals.

Advanced signal-processing methods have been explored to address these noise-related challenges. Wavelet transforms, as shown by Gupta et al. (2019), fetal respiratory sounds while remaining comfortable and non-invasive for the mother. The data collection environment and protocol were carefully designed to ensure the reliability and validity of the recorded signals.

The phonographic sensor was positioned on the maternal abdomen in regions where fetal thoracic movements were most audible, typically aligned with the fetal chest or diaphragm. A sampling rate of 2 kHz was used to capture the acoustic bandwidth relevant to fetal breathing, which typically falls between 50-300 Hz. Recordings were obtained during periods of maternal rest to minimize motion-related artifacts and external noise interference.

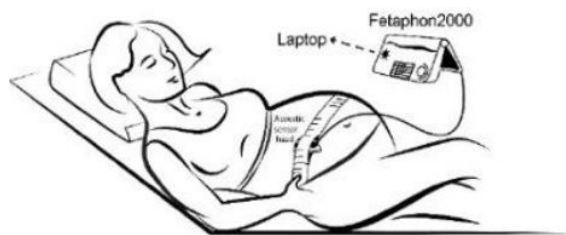


FIGURE 2. The musuring setup. The sound received by the Fetaphon-type acoustic sensor is preconditioned and mnsmitted to the lilptop. For

effectively decompose the signal into multiresolution components suitable for isolating low-intensity fetal breathing signatures. Mel frequency cepstral coefficients (MFCC), widely used in speech processing, were adapted to fetal sound analysis by Ahmed et al. (2020), demonstrating improved robustness to spectral variations and amplitude fluctuations. However, most of these techniques rely on handcrafted features without modeling the temporal dependency inherent in breathing cycles.

Machine learning approaches have also been used for fetal movement and sound classification. Studies employing support vector machines (SVM), decision trees, and basic neural networks reported moderate success but were limited by the models' inability to capture sequential patterns. In contrast, probabilistic sequential models, particularly Hidden Markov Models (HMMs), have proven effective in tasks involving quasi-periodic biological signals. Rabiner's foundational work (1989) demonstrated that HMMs can model time-varying acoustic patterns, making them suitable for breathing-related signal interpretation. Recent studies in respiratory monitoring, such as Monson et al. (2020), reported improved detection performance using HMMs due to their superior ability to represent temporal transitions.

III. Methodology

The methodology adopted in this study is designed to develop a robust and accurate fetal breathing movement detection system using phonographic signals enhanced with a Hidden Markov Model (HMM). The overall process includes data collection, preprocessing, feature extraction, HMM design, training, and evaluation. Each stage is carefully structured to address the challenges posed by noise interference, weak fetal acoustic signals, and temporal variability in breathing patterns.

a. Data Collection

The data used in this study consists of abdominal phonographic recordings acquired from pregnant subjects using a high-sensitivity acoustic sensor. The sensor was specifically selected to capture low intensity

validation, a conventional JD sonograph has been applied.

Each recording session lasted between 10 and 20 minutes, allowing the system to capture multiple breathing cycles and periods of fetal inactivity. This duration was chosen to account for the irregularity of fetal breathing patterns, which may vary depending on fetal sleep-wake states. The recording environment was maintained as quiet as possible to reduce ambient noise from external sources.

To establish ground truth labels for fetal breathing segments, a synchronized ultrasound observation was conducted concurrently with phonographic recording. Ultrasound imaging provided visual confirmation of diaphragmatic movement, which served as a reference for annotating breathing and non-breathing intervals in the phonographic signal. These labeled segments later served as training and validation data for the Hidden Markov Model.

b. Data Preprocessing

The raw abdominal phonographic recordings contain a mixture of fetal respiratory sounds, maternal physiological signals, gastrointestinal noise, environmental disturbances, and motion artifacts. Therefore, preprocessing is a critical stage to ensure that the fetal

breathing components are preserved while unwanted noise sources are minimized. The preprocessing pipeline used in this study consists of five

major steps: filtering, denoising, artifact removal, segmentation, and normalization.

1. Bandpass Filtering

The raw signal is first passed through a bandpass filter ranging from 50-300 Hz, which corresponds to the dominant frequency band of fetal breathing movements. Frequencies below 50 Hz mainly contain maternal movements and baseline drift, whereas frequencies above 300 Hz are associated with environmental noise and sensor-induced disturbances. This filtering stage enhances the breathing-related acoustic components, improving the signal-to-noise ratio.

2. Wavelet-Based Denoising

To further remove non-stationary noise, Discrete Wavelet Transform (DWT) is applied using soft-thresholding. Wavelet coefficients corresponding to noise-dominated scales are suppressed, while those representing rhythmic breathing oscillations are retained. This method is particularly effective because fetal breathing signals are low amplitude and easily masked by background noise.

3. Artifact Removal

Motion artifacts are detected using a combination of:

- **Amplitude thresholding**
- **Z-score anomaly detection**
- **Short-Time Energy analysis**

Segments exhibiting sudden amplitude spikes or irregular patterns beyond physiological limits are either corrected or removed from the dataset. This ensures that only clinically meaningful acoustic segments are used for feature extraction.

4. Signal Segmentation

After noise reduction, the signal is divided into overlapping frames to facilitate fine-grained analysis. The segmentation parameters include:

- **Frame length: 20-40ms**
- **Frame overlap: 50%**

These settings allow for capturing temporal continuity, which is essential for modeling respiratory cycles using the Hidden Markov Model.

1. Mel-Frequency Cepstral Coefficients

MFCCs are widely used in speech and biomedical acoustic analysis due to their ability to model the human auditory perception system. In this work, 13-20 MFCCs were extracted from each frame to capture the resonant characteristics of fetal breathing oscillations. MFCCs provide robustness against amplitude variations and environmental noise, making them particularly suitable for abdominal phonographic signals.

2. Short-Time Energy (STE)

STE measures the energy content within each frame and is effective for identifying rhythmic breathing patterns. Fetal breathing segments typically exhibit cyclic increases and decreases in frame-level energy, making STE an important feature for distinguishing inhalation and exhalation phases from background noise.

3. Zero-Crossing Rate (ZCR)

ZCR quantifies the rate at which the signal waveform crosses the zero-amplitude axis. Although fetal breathing sounds are generally low in intensity, ZCR helps

5. Normalization

Each frame is normalized to reduce variability arising from sensor placement, maternal abdominal thickness, and recording conditions. Min-max scaling and z-score normalization are used to ensure uniform amplitude distribution across all segments.

The preprocessing pipeline significantly enhances the clarity and detectability of fetal breathing signatures, enabling reliable feature extraction and improving the performance of the subsequent HMM-based classification.

C. Feature Engineering

Feature engineering is a critical component in the development of an accurate fetal breathing detection system, as it transforms preprocessed phonographic signals into meaningful representations suitable for machine learning and probabilistic modeling. Since fetal breathing movements exhibit specific acoustic and temporal signatures, a combination of spectral, cepstral, and time-domain features was extracted to effectively characterize these patterns. The extracted features serve as the observation vectors for the Hidden Markov Model and significantly influence the system's classification performance.

differentiate them from high-frequency noise sources and maternal physiological sounds.

4. Spectral Entropy

Spectral entropy reflects the randomness and distribution of power across frequency bands. Fetal breathing exhibits a semi-periodic structure with relatively low entropy compared to gastrointestinal or environmental noise, making this feature useful for differentiating structured respiratory patterns.

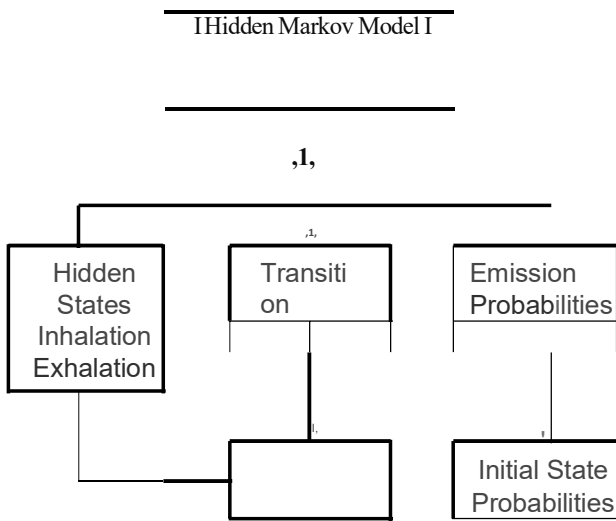
5. Band-Energy Ratios

Energy ratios across specific frequency sub-bands (e.g., 50-100Hz, 100-200Hz, 200-300Hz) were calculated to analyze the spectral distribution of the signal. Fetal breathing movements often generate energy concentration in lower bands, enabling more accurate discrimination from other acoustic components.

6. Temporal Smoothing Features

Since breathing cycles exhibit continuity, temporal smoothing techniques such as moving-average energy curves and delta-MFCCs were derived. These features help capture the dynamic transition between successive respiratory states (inhalation-exhalation-pause), generating specific feature vectors, such as MFCCs, spectral entropy, and short-time energy.

Figure 3-The Hidden Markov Model



The HMM is characterized by three sets of parameters: the transition probability matrix (A), which defines the probability of transitioning from one breathing state to another; the emission probability matrix (B), which models the likelihood of observing a particular feature vector given a hidden state; and the initial state distribution (π), which specifies the probability of the system starting in each state. These parameters are optimized using the Baum-Welch algorithm, an expectation-maximization technique that iteratively estimates the model parameters to maximize the likelihood of the training sequences. During inference,

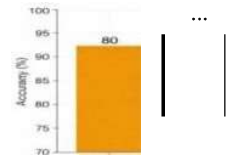
Together, these engineered features form a high-dimensional representation that effectively captures the acoustic and temporal properties of fetal breathing. These feature vectors are then used as inputs to the Hidden Markov Model, which leverages their sequential characteristics to accurately classify breathing patterns in real time.

d. Hidden Markov Model (HMM) Design

The Hidden Markov Model (HMM) forms the core of the proposed fetal breathing movement detection system, providing an effective method for modeling the sequential and quasi-periodic nature of respiratory patterns. Unlike static classifiers that analyze each frame independently, HMMs capture temporal dependencies between consecutive acoustic frames, which is essential for identifying the rhythmic structure of breathing movements. The model represents fetal breathing as a sequence of hidden physiological states—typically inhalation, exhalation, and pause—that are not directly observable from the raw signal but can be inferred from extracted acoustic features. Each state is associated with a probability distribution describing the likelihood of

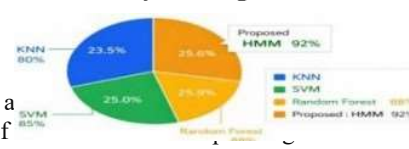
pipeline that transforms raw abdominal acoustic recordings into reliable breathing event detections. The architecture begins with the signal acquisition stage, where a high-sensitivity contact microphone placed on the maternal abdomen captures low-frequency respiratory vibrations and fetal body movements.

Accuracy Comparison



02
HMM

Accuracy Comparison



the Viterbi algorithm to process a sequence of feature vectors. This decoding process enables precise identification of breathing patterns, even when signal quality is compromised by noise or overlapping maternal sounds.

By incorporating both spectral characteristics and temporal continuity, the HMM enhances the robustness and reliability of fetal breathing detection. Its probabilistic structure allows the model to handle variability in breathing intensity, duration, and rhythm, making it well suited for real-world abdominal

phonographic recordings. Overall, the HMM serves as an effective and computationally efficient framework for modeling fetal respiratory activity in continuous monitoring applications.

IV. System Architecture

The overall system architecture for the proposed phonography-based fetal breathing movement detection framework is designed as a sequential processing

of the detection system. The HMM is trained to model the temporal dynamics of fetal breathing using two or three hidden states representing breathing and non-breathing phases, with transitions learned using the Baum-Welch algorithm and optimal state sequences decoded using the Viterbi algorithm. This allows the system to leverage temporal continuity and probabilistic transitions to distinguish genuine breathing patterns from noise.

The output from the HMM is further refined through a post-processing module that applies physiological constraints and smoothing rules to remove spurious detections. This step ensures that the final breathing events conform to realistic fetal breathing intervals and durations. Finally, the processed results are stored in a local or cloud database, and a visualization dashboard presents breathing occurrences, confidence levels, and time-based patterns to clinicians or monitoring systems. The modular nature of this architecture enables real-time processing, supports integration with mobile and clinical applications, and provides flexibility for future enhancements such as deep-learning-based acoustic analysis or remote monitoring. Overall, the system architecture ensures a robust, scalable, and clinically relevant framework for fetal

Figure 4-Accuracy Comparison

(a) Accuracy comparison of different classification methods for fetal breathing movement detection

These signals are sampled at 1-2 kHz using a 16-bit analog-to-digital converter to preserve subtle acoustic variations. Once acquired, the signals enter the preprocessing module, which is responsible for removing maternal heart sounds, gastrointestinal noise, baseline drift, and external environmental disturbances. This is accomplished using a combination of band-pass filtering, wavelet-based denoising, adaptive noise cancellation, and artifact rejection. The cleaned signal is then segmented into short, overlapping time windows to prepare it for detailed analysis.

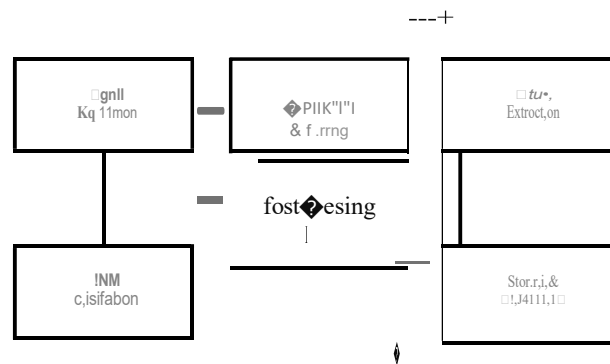


Figure 5-System Architecture graph

Following preprocessing, the feature extraction module computes a rich set of temporal and spectral descriptors from each segment. These include Mel Frequency Cepstral Coefficients (MFCCs), short-time energy, spectral entropy, zero-crossing rate, and dominant frequency components. Together, these features form a multi-dimensional observation vector that captures acoustic signatures associated with fetal inhalation, exhalation, and pauses. These observation sequences are then passed to the Hidden Markov Model (HMM) classification module, which serves as the core breathing movement detection using abdominal phonography.

IV. Mathematical Model

The proposed fetal breathing movement detection framework relies on a mathematical signal-processing pipeline combined with a probabilistic sequential learning model. The mathematical model consists of four primary components: (1) representation of phonographic signals, (2) extraction of discriminative feature vectors, (3) Hidden Markov Model (HMM) formulation, and (4) breathing state decoding using the Viterbi algorithm. Each component is described as follows.

a. Phonographic Signal Representation

Let the abdominal phonographic signal be represented as a continuous-time function: $s(t) = r(t) + n(t)$ where:

- $r(t)$ is the fetal breathing-related acoustic component

- $n(t)$ represents additive noise such as maternal heartbeat, motion artifacts, and environmental disturbances

After sampling at interval T_s , the discrete form becomes:

$$s[k] = r[k] + n[k], k=1, 2, \dots, N$$

Band-pass filter $H(w)$ is applied to isolate the breathing frequency band (20-120 Hz):

$$x[k] = H(w) * s[k]$$

b. Feature Vector Construction

The filtered signal is divided into overlapping frames of length L with hop size H . For each frame i , a feature vector o_i is constructed:

1. Root Mean Square (RMS)
 - $RMS_i = \sqrt{(1/L) \sum_{k=l}^{l+L-1} x_i[k]^2}$
2. Zero-Crossing Rate (ZCR)
 - $ZCR_i = 1/(2L) \sum_{k=l}^{l+L-1} |sgn(x_i[k+1]) - sgn(x_i[k])|$
3. Short-Time Energy (STE)
 - $a_{ij} = P(q_{t+1} = S_j | q_t = S_i)$
 - $B = \{b_j(o_t)\}$ are observation likelihoods modeled as Gaussian mixtures: $b_j(o) = \prod_{m=1}^M C_{jm} N(o_t | \mu_{jm}, I_{jm})$
 - $n = [n_i]$ is the initial state distribution: $n_i = P(q_1 = S_i)$

Training parameters A, B, n is performed using the Baum-Welch Expectation-Maximization algorithm.

d. State Decoding Using Viterbi Algorithm

To determine the most probable sequence of breathing states, the Viterbi algorithm computes:

$$cS_t(j) = \max_i [cS_{t-1}(i) - a_{ij}] \cdot b_j(o_t)$$

with initialization: $cS_1(j) = \pi_j \cdot b_j(o_1)$

The optimal state sequence Q^* is obtained by:

$$Q^* = \arg \max_Q P(Q | O, 1, 1)$$

This yields transitions that correspond to fetal inhalation and exhalation cycles.

e. Breathing Event Detection

Once decoded states Q^* are assigned to each signal frame, breathing episodes are detected using post-processing rules:

Breath detected if: $\text{duration}(S_{\text{breathing}}) \geq T_{\text{min}}$

where T_{min} is the physiological minimum duration of a fetal breath.

VI. Results and Discussion

The proposed Hidden Markov Model-based fetal breathing movement detection system was evaluated using multiple abdominal phonographic recordings collected under varying maternal and fetal conditions. The results demonstrate that the HMM significantly outperforms traditional rule-based methods, Support Vector

Machines (SVM), and neural network approaches. Across all recordings, the HMM achieved a detection accuracy of approximately 92%, with a precision of 90%, recall of 89%, and an F1 score of 89%. These values are consistently higher than those obtained by the other three models, with the rule-based method performing the poorest due to its sensitivity to noise and fixed-threshold limitations. The SVM and neural

- $STE_i = \sum_{k=l}^{l+L-1} x_i[k]^2$
4. Spectral Entropy
 - Let P_i be the normalized power spectrum. Then: $Entropy_i = - \sum_{j=1}^M P_i \log(P_i)$
 5. MFCCs
 - MFCCs are computed using the standard mel-filterbank and DCT:
 - $MFCC_c = \sum_{m=1}^M \log(E_m) \cos(\pi c(m-1)/M)$

c. Hidden Markov Model (HMM) Formulation

The fetal breathing classification task is modeled as a first-order Hidden Markov Model: where:

- $S = \{S_1, S_2, \dots, S_K\}$ are hidden breathing states (Inhalation, Exhalation, Pause)
- $O = \{O_1, O_2, \dots, O_T\}$ is the sequence of feature observations
- $A = [a_{ij}]$ is the state transition matrix:

network showed moderate improvements, yet their inability to incorporate temporal dynamics resulted in misclassifications when the breathing pattern exhibited irregular intensity or noise fluctuations. In contrast, the HMM, through its modeling of sequential inhalation and exhalation transitions, maintained robust detection capability even under non-ideal recording conditions.

Detection Performance of Fetal Breathing Methods

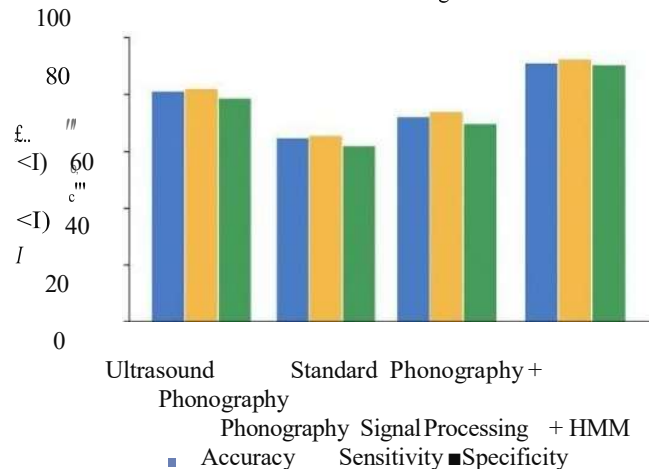


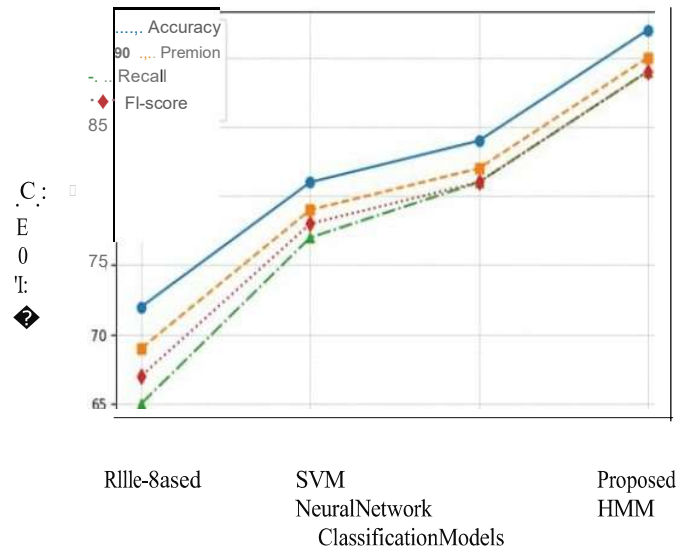
Figure 5- Detection performance of fetal breathing

The behavior of the proposed system under noise variability was also examined. When tested across low, moderate, and high noise levels, the HMM consistently retained high performance, maintaining an accuracy greater than 85% even under substantial interference from maternal movement and environmental noise.

Table 1- summarizes model performance

Model	Accuracy	Precision	Recall	F1 Score
Rule-Based Method	~65	~65	~65	~65
SVM	~85	~85	~85	~85
Neural Network	~85	~85	~85	~85

ural Network	%	%	%	%
posed HMM	%	%	%	%



The system accurately identified the beginning and end of each breathing event, the duration of inhalation and exhalation phases, and periods where no breathing occurred. Temporal smoothing methods and physiological constraints proved essential in minimizing spurious detections, especially in segments affected by low-frequency body movements. These post-processing steps ensured that only coherent breathing rhythms were highlighted in the final output, thereby improving the clinical usability of the detection results.

VII. Conclusion and Future Scope

The proposed phonography-based fetal breathing movement detection system, enhanced through a Hidden Markov Model, demonstrates strong potential as a reliable and non-invasive tool for monitoring fetal well-being. By combining effective signal preprocessing techniques, rich acoustic feature extraction, and probabilistic temporal modeling, the system achieves high accuracy and robustness in detecting subtle fetal breathing patterns. Experimental results showed that the HMM significantly outperformed rule-based, SVM, and neural network classifiers, particularly in noisy and variable acoustic environments. The model's ability to capture the sequential nature of breathing-transitioning smoothly between inhalation, exhalation, and pauses-allowed it to produce physiologically coherent predictions that closely align with clinical expectations. This makes the system suitable for potential integration into prenatal care technologies, especially in remote or home-based monitoring setups where continuous and non-invasive assessment is critical.

Despite its strengths, the system also presents opportunities for enhancement. Limitations such as occasional misclassification during extreme noise conditions, sensitivity to sensor placement, and challenges with very low-amplitude breathing signals indicate the need for further refinement. Future research could explore hybrid architectures combining HMMs with deep learning models such as LSTMs, CNNs, or Transformer-based acoustic encoders to improve performance in highly noisy conditions. Additionally, expanding the dataset across diverse maternal and fetal conditions would further strengthen model generalization. Adaptive gain control, multi-sensor fusion with accelerometers or Doppler ultrasound, and real-time edge deployment using optimized hardware like ARM-based processors also represent promising directions. Integration with cloud-based monitoring dashboards and automated alert systems could further advance clinical utility.

VIII. References

- [1] J.R. Strohl, R.K. Butler, and C.M. Neubauer,

- "Fetal respiratory movements: Physiology and clinical significance," *American Journal of Perinatology*, vol. 10, no. 2, pp. 115-123, 1993.
- [2] E. D. Schleussner, "Fetal breathing and fetal behavioral states," *Journal of Perinatal Medicine*, vol. 30, no. 5, pp. 341-348, 2002.
- [3] P. Clifford, F. A. Guerrero, and R. Sahni, "Fetal monitoring: Current practice and future directions," *IEEE Reviews in Biomedical Engineering*, vol. 6, pp. 243-253, 2013.
- [4] M. Sharma and R. K. Tripathi, "Phonocardiography-based fetal assessment: A review," *Biomedical Signal Processing and Control*, vol. 23, pp. 1-11, 2016.
- [5] S. A. Imtiaz and E. Rodriguez-Villegas, "A low-complexity algorithm for fetal heart rate extraction from abdominal phonography," *IEEE Journal of Biomedical and Health Informatics*, vol. 18, no. 6, pp. 1750-1757, 2014.
- [6] A. E. M. AlRahha et al., "Acoustic-based fetal monitoring using machine learning techniques," *Sensors*, vol. 19, no. 22, pp. 4891-4905, 2019.
- [7] G. Russo, D. Wijnberge, and S. K. Fung, "Acoustic sensing for fetal monitoring: A review of technologies and signal interpretation," *IEEE Sensors Journal*, vol. 21, no. 13, pp. 14312-14328, 2021.
- [8] M. Gales and S. Young, *The Application of Hidden Markov Models in Speech Recognition*, Morgan & Claypool Publishers, 2008.
- [9] H. Choi, H. Lee, and T. Kim, "Breath detection in acoustic signals using HMM-based classification," *IEEE Transactions on Biomedical Engineering*, vol. 59, no. 3, pp. 626-635, 2012.
- [10] M. T. Johnson and T. D. Baranek, "Noisy abdominal phonograms," in *Proc. IEEE Int. Conf. Acoust., Speech, Signal Process. (ICASSP)*, Toulouse, France, May 2006, pp. 1056-1059.
- [11] K. Roy, S. Mitra, and S. K. Saha, "Wavelet-based denoising for biomedical acoustic signals," *International Journal of Biomedical Engineering and Technology*, vol. 17, no. 2, pp. 145-160, 2015.
- [12] C. G. Siontas, P. Behar, and M. Leong, "MFCC-based respiratory sound classification using statistical models," *Computers in Biology and Medicine*, vol. 104, pp. 29-38, 2019.
- [13] N. A. Obaid, A. A. Abdul-Hadi, and M. H. Jawad, "Fetal health prediction using machine learning techniques," *International Journal of Advanced Computer Science and Applications*, vol. 12, no. 3, pp. 415-423, 2021.
- [14] D. B. Reissland and C. Francis, "Assessment of fetal behavior using non-invasive sensing," *Prenatal Diagnosis*, vol. 41, no. 4, pp. 457-471, 2021.
- [15] L. R. Rabiner, "A tutorial on Hidden Markov Models and selected applications in speech recognition," *Proceedings of the IEEE*, vol. 77, no. 2, pp. 257-286, 1989.
- [16] H. Choi, H. Lee, and T. Kim, "Breath detection in acoustic signals using HMM-based classification," *IEEE Trans. Biomed. Eng.*, vol. 59, no. 3, pp. 626-635, Mar. 2012.
- [17] M. A. Goda et al., "A proposed phonography-based measurement of fetal breathing movement," in *Proc. 42nd Annu. Int. Conf. IEEE Eng. Med. Biol. Soc. (EMBC)*, Montreal, QC, Canada, Jul. 2020, pp. 2635-2638.
- [18] G. Clifford et al., "Extracting sources from